Voltage, A2D, Piece Wise Linear, Noise

ENSC351

Slides #7

© Dr. B. Fraser (updated M. Stewart)

Topics

- What form are real-world signals?
- How can a computer read an analog signal?
- How can we approximate functions?

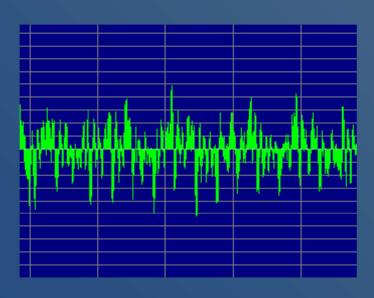
Signals in the "Real World": Voltage

25-9-26

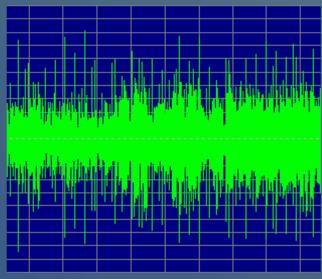
-3

Voltage

- Real world analog signals are often changes in voltage:
 - Ex: Microphone encodes sound into voltage levels



Audio: Zoomed in

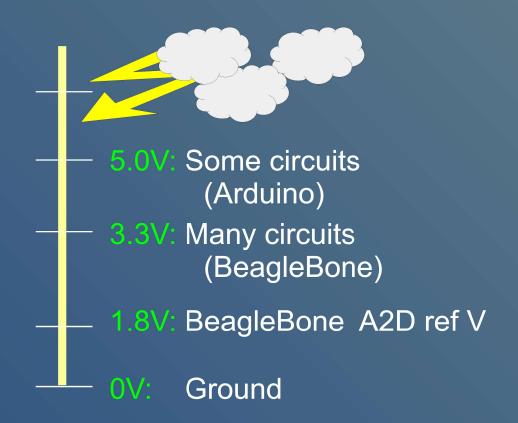


Audio: Zoomed out

Voltage Ranges

These are all DC voltage (Direct Current)

Out of the wall comes AC Voltage (Alternating Current)

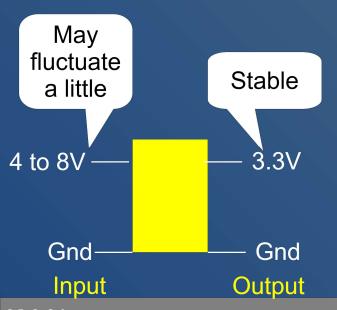


Electronics Components ("Parts")

 Many electronics components run on, manage, and work with voltages.

Voltage Regulator:

Converts input voltage to stable output voltage.



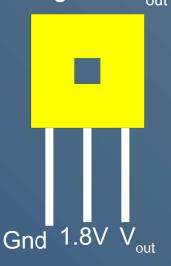
Potentiometer:

Turning the knob adjusts the output voltage on V_{out}.



Light Sensor:

The more light, the lower the voltage on V_{out}



Reading a Voltage

- How can we read a signal into the computer?
 - Real world is analog voltages; computer are digital.
 - We need an analog to digital converter (ADC)
 - Also called an A2D (Analog "to" Digital)
- BeagleBone has a 12 bit A2D:
 - It reads a voltage and gives a number between 0 and 2^{12} -1 (=4095)
 - It can sample voltages between 0V and 1.8V
 - It is easily damaged by higher voltages!

Quantization & Sampling

Quantization:

Since it has 4096 samples over 1.8V

Resolution of a single bit is:
 1.8V / 4096 = 0.00044V = 0.44 mV
 This is pretty good for most applications!

Sample Rate:

How fast the A2D can read samples

- Need 44100 Hz (44.1kHz) for CD audio
- BeagleBone can sample at 1.6MHz (1600kHz)
- Some applications (reading a POT for volume) may need low sample rates (~10Hz)

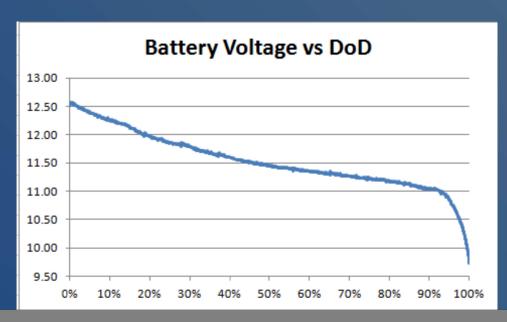
BBB A2D Demo for POT

- A2D is enabled by default
 - Done for us by UBoot via /boot/uEnv.txt
- Change to sys file system folder:
 (bbg) \$ cd /sys/bus/iio/devices/iio\:device0
- Read voltage 0 (for POT):
 (bbg) \$ cat in_voltage0_raw

Approximating Functions: Piece Wise Linear

Function Approximations

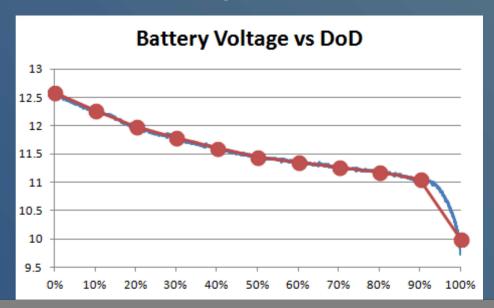
- Real world functions can be hard to approximate.
 - Some approximations are computationally expensive (high-order polynomials, cubic-spline, ..)
 - Piecewise Linear (PWL)
 Approximate a function with a series of lines.



As you discharge a battery, its voltage drops.
(DoD is Depth of Discharge)

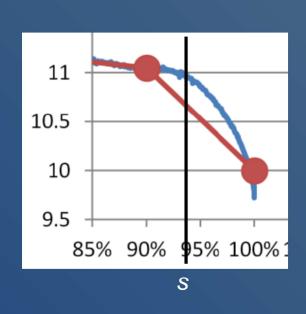
Piece Wise Linear

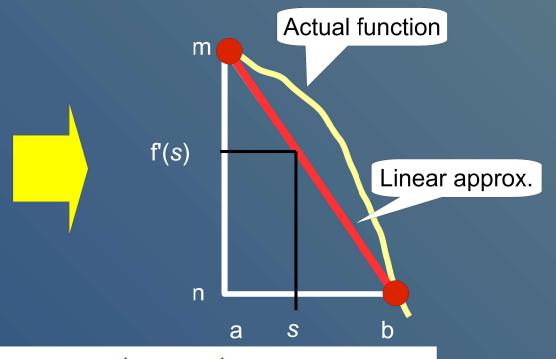
- Pick good points on the function f(x) to capture its shape
 - can be evenly spaced, or
 - can be specially selected points
- Between adjacent points, draw a straight line.
- The approximation f'(x) is the straight lines.



Computing Piecewise Linear

- Given an input value s, use points on either side
- Compute f'(s) by solving the point on the line

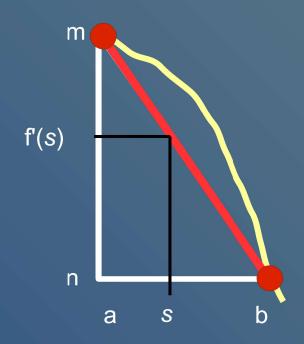




$$f'(s) = \left(\frac{s-a}{b-a}\right) \cdot (n-m) + m$$

Understanding Piecewise Linear

$$f'(s) = \left(\frac{s-a}{b-a}\right) \cdot (n-m) + m$$



Piecewise Linear Details

Some extra notes:

- If a reading is < min or > max data point, clip it to min & max.
- Enter the points into a program as two arrays:

```
#define PIECEWISE_NUM_POINTS 11
const float PIECEWISE_DoD[] = { . 0, . . 1, . . . . 8, . . 9, . 1};
const float PIECEWISE_V[] = {12.6, . 12.3, . . . . 11.2, . 11.1, . 10};
```

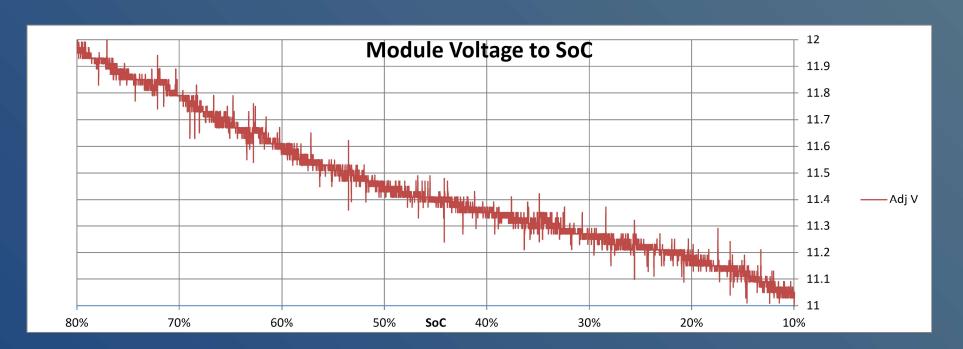
- Make sure to use the correct data types for your calculation (possibly floating point).
- Watch for array out of bounds!



Noise

- Real world data is often 'noisy'
 - each sample has..
 causing it to differ from the correct real-world value.

A2D Sample = (precise real-world value) + (noise)



Problem with Noise

- A noisy signal's fluctuations may be:
 - changes in the real signal
 - noise
- Ex: Turn off phone when battery is empty (3V)

```
static void powerDownIfBatteryDead() {
    if (batteryVoltage < 3.0) {
        powerDown();
    }
}</pre>
```

What happens when noise spike gives you 2.99V reading when battery actually at 3.10V?

Tolerating Noise: N Samples Past Threshold

An idea to tolerate some noise:...

Ex: Power off if 5 consecutive samples are less than 3V:

```
static double batteryVHistory[5];
static void powerDownIfBatteryDead() {
    for (int i = 0; i < 5; i++) {
        if (batteryVHistory[i] >= 3.0) {
            return;
        }
     }
    powerDown();
}
```

Tolerating Noise: Hysteresis

State machine should be stable:...

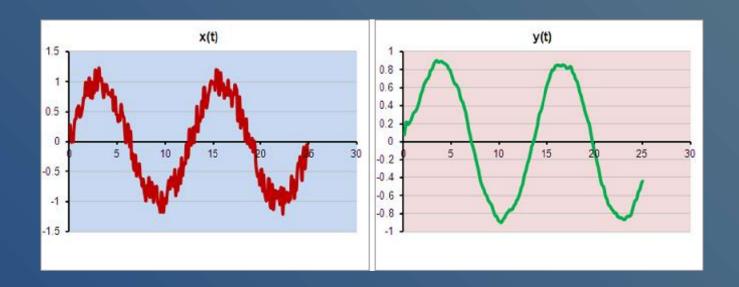
```
- Problematic Example:
  Battery-saver when State of Charge < 30%
  static bool inLowPower = false;
  static void manageLowPowerState() {
     if (batterySoC < 30) {
        inLowPower = true;
     } else {
        inLowPower = false;
     }
}</pre>
```

Problem?

Hysteresis Solution

A solution:

```
static bool inLowPower = false;
static void manageLowPowerState() {
   // Enter
   if (batterySoC < 30) {
      inLowPower = true;
   // Exit (5% SoC Hysteresis)
   if (batterySoC > 35) {
      inLowPower = false;
```



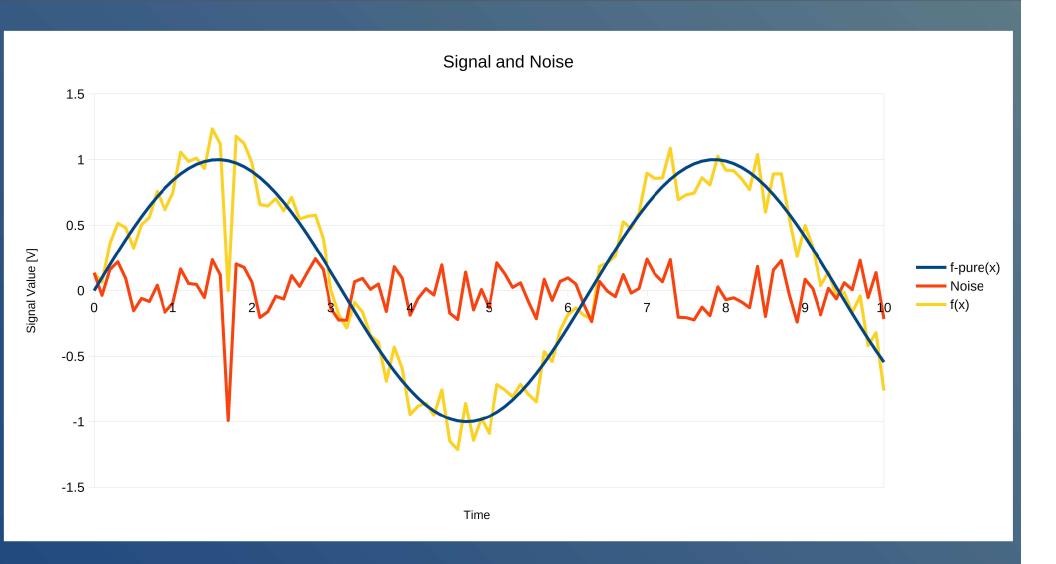
Noise Filters

Simple Moving Average

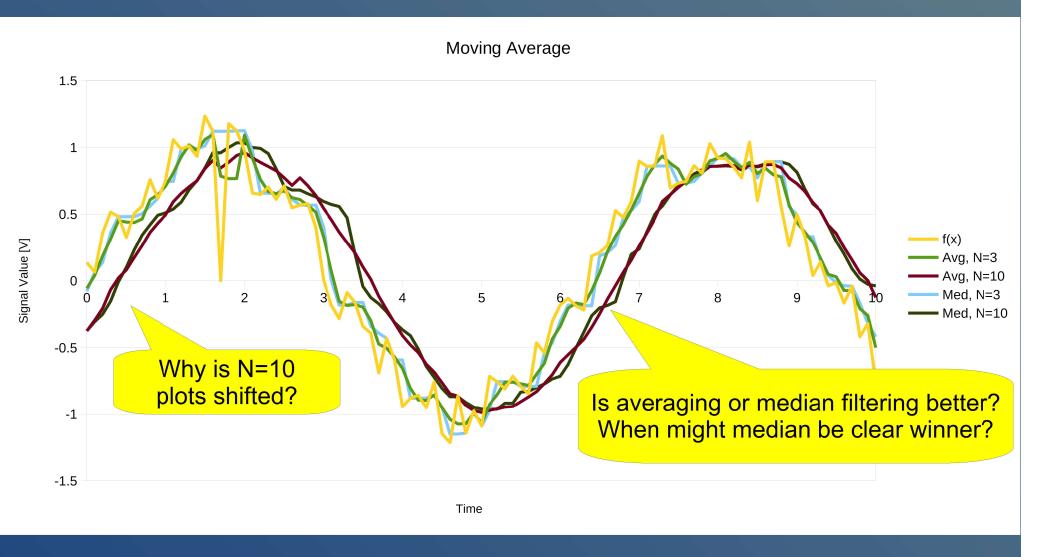
- Rather than tolerating noise,...
- Maintain buffer of previous N samples

```
static double batteryVFiltered = 0;
      static double samples[10];
      static int nextldx = 0;
      static void getNewBatetryV() {
          // Sample
           samples[nextIdx] = readA2DVoltage();
           nextIdx = (nextIdx + 1) \% 10;
          // Filter
           batteryVFiltered = average(samples, 10);
           //batteryVFiltered = median(samples, 10);
static double average(double *data, int numValues) {...}
Note: Must also handle non-full buffer.
```

Noise Example



Simple Moving Average Effectiveness



Exponential Smoothing

Simple moving average equally weights all samples,
 ...

- Exponential Smoothing Details
 - Let s_n be the Nth sample from the A2D
 Let v_n be the Nth filtered value
 Let a be a weighting value between 0 and 1
- Smoothed Data Points (v_n)

$$V_0 = S_0$$

 $V_n = a * S_n + (1 - a) * V_{(n-1)}$

Exponential Smoothing Intuition

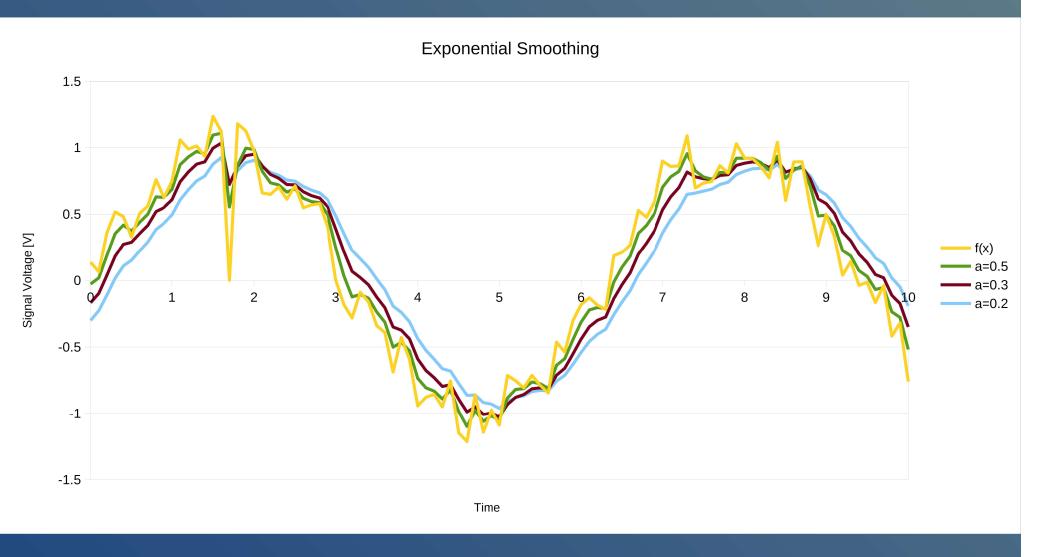
- s_n is the Nth sample from the A2D
 v_n is the Nth filtered value
 a is a weighting value between 0 and 1
- Smoothed Data Points (v_n)

$$V_0 = S_0$$

 $V_n = a * S_n + (1 - a) * V_{(n-1)}$

- Intuition
 - a = 1: 100% weight on instantaneous 'now' sample (filtering disabled)
 - a = 0.1: Very heavy weight on old data, not much on new data (average over very long time frame)

Exponential Smoothing Effectiveness



Summary

- Many sensor generate analog voltage signals.
 - Be careful that signal is in correct voltage range!
- BBB can sample voltages between 0 and 1.8V
 - 12-bit A2D: digital values between 0 and 4095
- Piecewise Linear approximates functions
 - Given a reading (on the X axis),
 use the selected points and straight lines to approximate desired value (on the Y axis)
- Noise adds errors to samples
 - Tolerate nose with hysteresis and filter thresholds
 - Filter with simple moving average or exponential smoothing.