ENSC 351 Processes & Threads

Dr. Matthew Stewart

Slides for course derived from Dr. Mohamed Hefeeda's slides Updated by Dr. Brian Fraser

Objectives

□ Understand

- Process concept
- Process scheduling
- Creating and terminating processes
- Interprocess communication
- Threads vs Processes

Process Concept

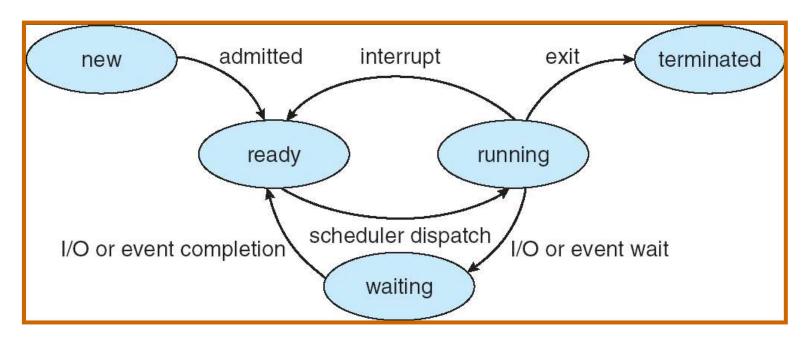
☐ Process is... Process execution must progress in sequential fashion ❖ A program may exist on the hard drive, but is not a process until being executed (usually from memory) ☐ Note: Terms... are interchangeable ☐ A process includes: * program counter * stack pointer data section (memory) code section (memory)

Process in Memory

```
max
static int global = 0;
                                                                     stack
int main (int arg)
    float local;___
    char *ptr;____
    ptr = malloc(100);
    local = 0;
    local += 10*5;
                                                                     heap
                                                                     data
    foo();
     .... /* return addr */
                                                                     text
                                                          0
    return 0;
```

Process State

- ☐ As a process executes,...
 - * new:just created
 - instructions are being executed
 - process is waiting for some event to occur
 - process is waiting for CPU
 - * terminated: process has finished execution



(PCB)

• •

- ☐ OS maintains info about process in PCB
 - Process state
 - Program counter
 - CPU registers
 - CPU scheduling info
 - Memory-management info
 - Accounting info
 - I/O status info
- □ PCB used to...
 - ❖ E.g., to switch CPU from one process to another
- ☐ Typically, a large C structure in kernel
 - Linux: struct task_struct

process state
process number
program counter

registers

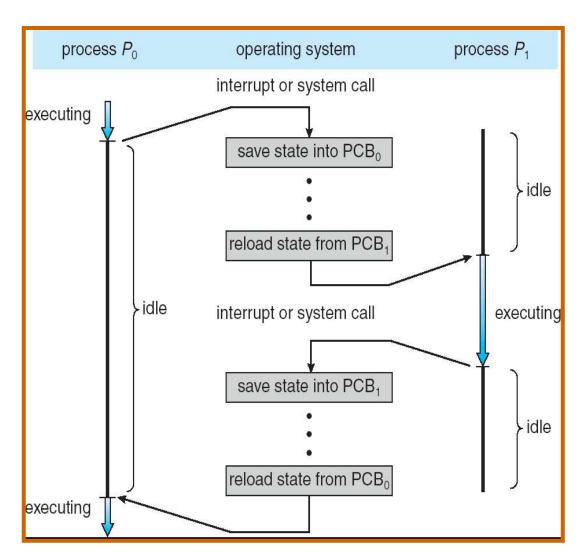
memory limits

list of open files

. . .

CPU Switch From Process to Process

- ☐ When switching from P_0 to P_1 kernel will:
 - ❖ Save state of P₀
 in PCB₀
 (in memory)
 - Load state of P₁ from PCB₁ into registers
- State = values of the..



CPU Switch From Process to Process cont'd

☐ Switching between processes is called a

• •

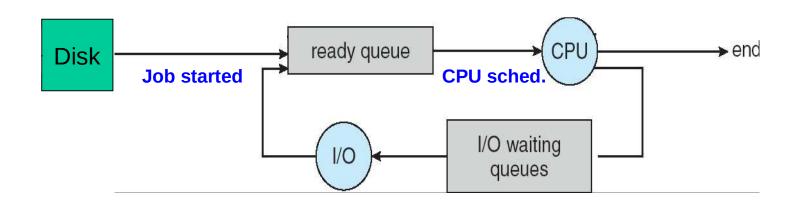
- ☐ Context-switch time is.. no useful work is done
- ☐ Switching time depends on hardware support
 - ❖ Some systems (Sun UltraSPARC) provide multiple register sets → very fast switching (just change a pointer)
 - Typical systems, few milliseconds for switching

Job Types

☐ Jobs (Processes) can be described as either:

- **..**
 - spends more time doing I/O than computations, many short CPU bursts
 - Often characteristic of interactive programs
 - Example: GUI, word processor, IDE
- **..**
 - spends more time doing computations; long CPU bursts
 - Example: factoring a large prime (cryptography)

Scheduling: The Big Picture (cont'd)

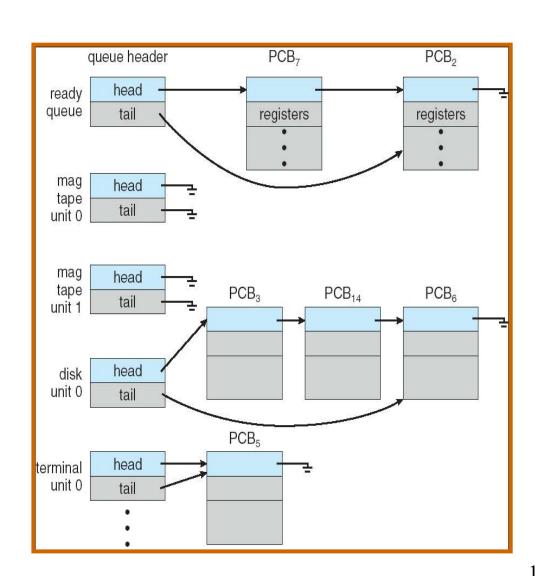


Schedulers (cont'd)

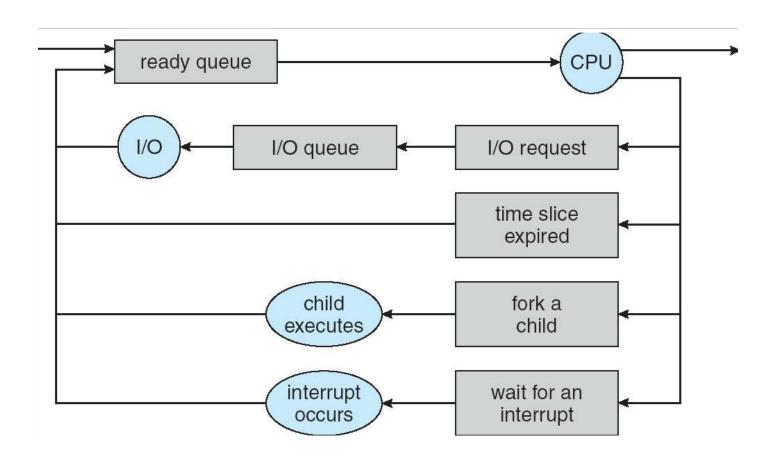
- ☐ Short-term scheduler (or CPU scheduler)
 - selects which process should be...
 and allocates CPU to it
 - Short-term scheduler is invoked.. (milliseconds)
 - So must...

Scheduling Queues

- ☐ Processes migrate among various queues
- set of all processes in the system
- set of all processes residing in main memory, ready and waiting to execute
- set of processes waiting for a specific I/O device

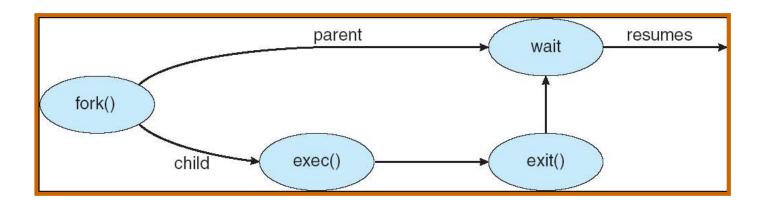


Process Lifetime



Process Creation: Unix Example

- ☐ Process creates another process (child) by using fork system call
 - Child is...
 - ❖ Typically, child loads another program into its address space using exec system call
 - **❖** Parent waits for its children to terminate



C Program Forking Separate Process

```
int main()
                                             Fork returns:
  /* fork another process */
                                            < 0:
  pid t pid = fork();
                                              0:
                                            > 0:
  if (pid < 0) { /* error occurred */</pre>
      fprintf (stderr, "fork Failed");
      exit(-1);
  else if (pid == 0) { /* child process */
                                               Replace child with
      execlp ("/bin/ls", "ls", NULL);
                                                 new program.
                 /* parent process */
  else {
      /* parent will wait for child to complete */
      wait (NULL);
      printf ("Child %d Completed", pid);
      exit(0);
```

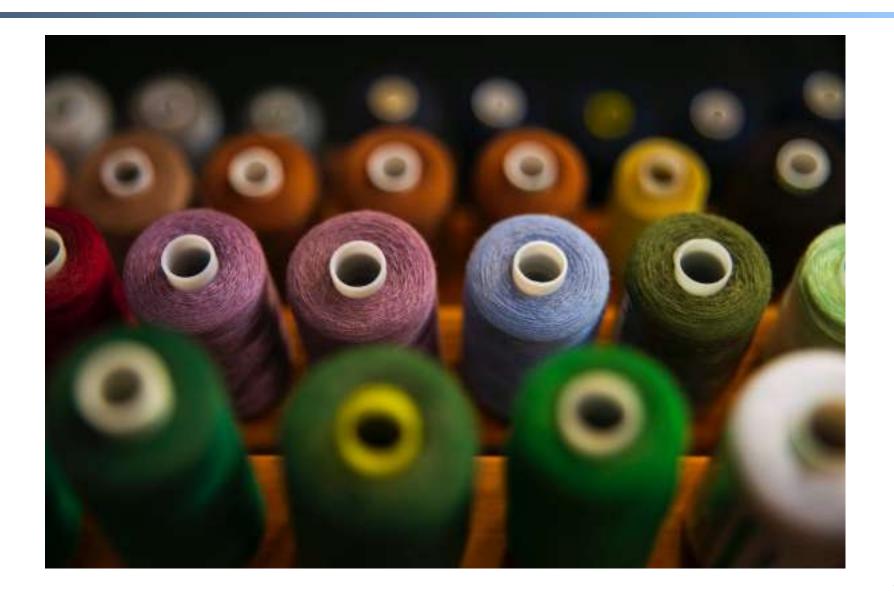
Tree of processes on BeagleBone Green

```
debian@BeagleBone:~$ pstree -l
systemd——3*[agetty]
          -avahi-daemon——avahi-daemon
          -cron
          -dbus-daemon
         -nginx---nginx
         -node-red---10*[{node-red}]
         -rpcbind
         -rsyslogd---3*[{rsyslogd}]
         -sshd---sshd---bash---pstree
         -systemd---(sd-pam)
         -systemd-journal
         -systemd-logind
         -systemd-network
         -systemd-resolve
         -systemd-timesyn---{systemd-timesyn}
         -systemd-udevd
          wpa supplicant
```

Process Termination (Linux)

- - Child has exceeded allocated resources
 - Task assigned to child is no longer required

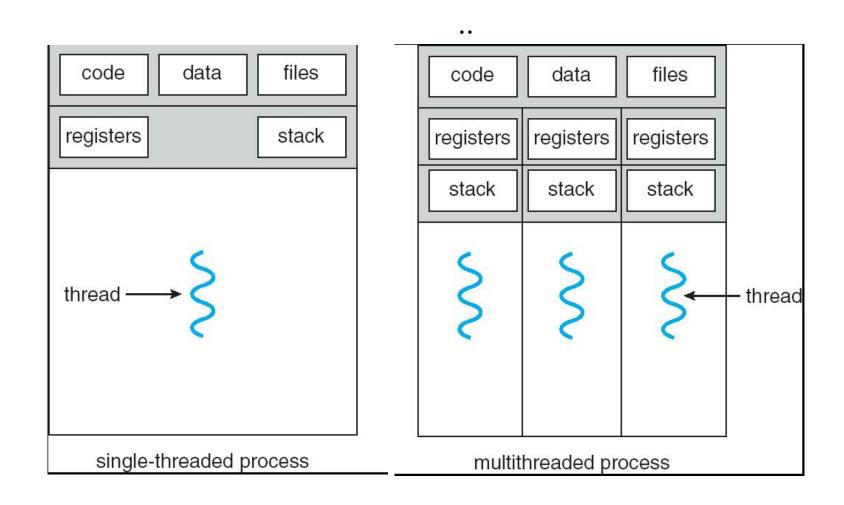
Threads



Thread Definitions

☐ Thread is a basic unit of CPU utilization * A sequence of instructions enclosed in a function which... ☐ Process is a program in execution **❖** A process is composed of.. ☐ Each thread has a thread control block (TCB) Program counter Register set, and Stack ☐ Threads of the same process share Code section Threads of a process... Data section OS resources such as open files and signals

Single and Multithreaded Processes



Why Multithreading?

□ Responsiveness: one thread for □ Resource Sharing: similar requests handled by the same code and use same files/resources ☐ Economy: threads are much cheaper to create/delete than... ☐ Utilization of multiprocessors: single threaded-process can NOT make use of multiple processors ■ Examples of multithreaded applications? Web browsers: parallel downloads **❖** Web servers: handle multiple concurrent clients Word processors: spell check in the background

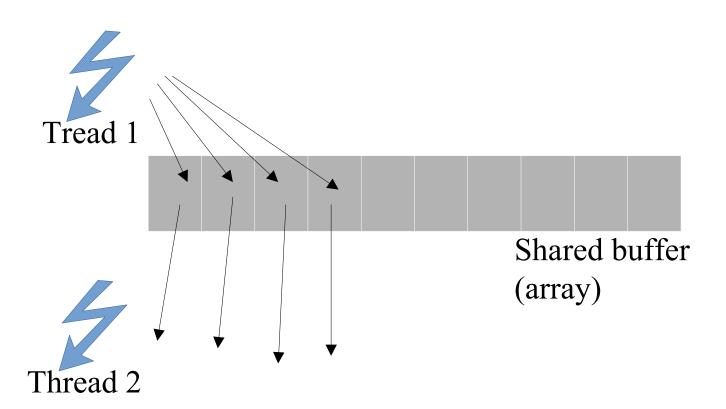
❖ Many others ...

Cooperating Processes

- □ Cooperating process can affect the execution of each other
- Why processes cooperate?
 - Information sharing
 - Computation speed-up
 - ❖ Modularity, Convenience
- ☐ Interprocess Communication (IPC) methods
 - Shared memory
 - Message passing

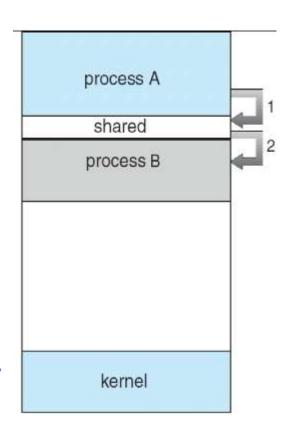
Threads & Shared Memory

- ☐ Threads inside a process share a memory space
 - ❖ Therefore, they can just use pointers to reference shared memory



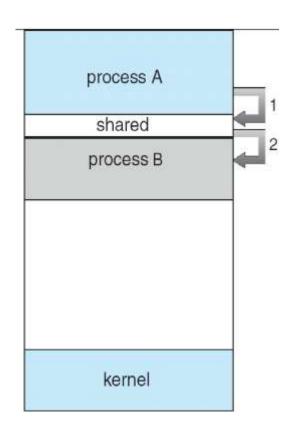
IPC: Shared Memory

- ☐ Processes communicate by creating a shared place in memory
 - One process creates a shared memory—shmget()
 - Other processes attach shared memory to their own address space shmat()
 - Then, shared memory is treated as regular memory
 - Synchronization is needed to prevent concurrent access to shared memory (conflicts)



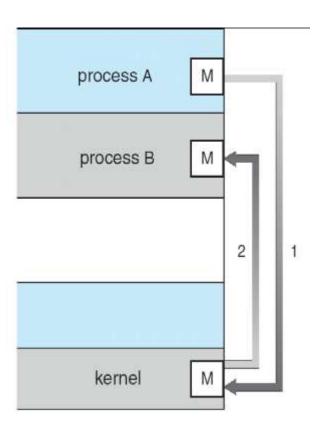
IPC: Shared Memory

- □ Pros
 - (use at memory speed)
 - Convenient to programmers (just regular memory)
- ☐ Cons
 - Need to.. (tricky for distributed systems)



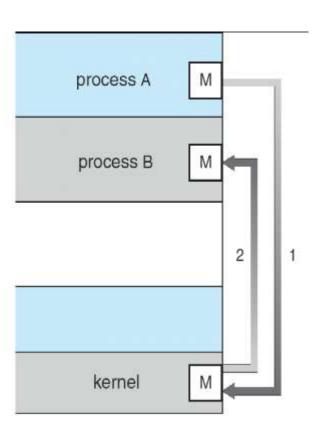
IPC: Message Passing

- ☐ If processes (or threads) *P* and *Q* wish to communicate, they need to:
 - * establish a communication
 - exchange messages via a pipe:
 - send (message) message size fixed or variable
 - receive (*message*)



IPC: Message Passing

- ☐ Pros
 - No conflict: easy to exchange messages especially in distributed systems
- ☐ Cons
 - Overhead (message headers)
 - **.**..
 - Sender must prepare messages; receiver must process them.
 - ...
 sender → kernel → receiver
 (several system calls)



IPC: Message Passing (cont'd)

- ☐ Synchronization: message passing is either
 - **..**
 - send () has sender block until message is received
 - receive () has receiver block until message is available
 - ***** ..
 - send () has sender send message and continue
 - receive () has receiver receive a valid message or null
- ☐ Buffering: Queue of messages attached to communication channel
 - Zero capacity Sender must wait for receiver (rendezvous)
 - Bounded capacity Sender must wait if link full
 - Unbounded capacity Sender never waits

Example: Linux Pipes

☐ Pipe:

Good for inter-thread and inter-process communication.

□ Needed Functions:

- pipe() to create file descriptors for read and write ends of pipe.
- fdopen() to open the pipe (from descriptor)
- fprintf() to write (or other functions)
- fgets() to read [blocking] (or other functions)
- close() to close the file descriptor.

Example: Linux Pipes code

```
// File descriptors for two ends of pipe
        int fds[2];
        pipe (fds);
                                  // Create a pipe.
        // Writer: Convert the write file descriptor to a FILE object
        FILE* streamW = fdopen (fds[1], "w");
        fprintf (streamW, "Hello World of Pipes!\n");
        fflush (streamW);
        close (fds[1]);
This possibly in different process/thread:
        // Reader: Convert read file descriptor to a FILE object.
        FILE* streamR = fdopen (fds[0], "r");
        // Read until end of the stream.
        char buffer[1024];
        while (!feof (streamR) && !ferror (streamR)
                 && fgets (buffer, sizeof (buffer), streamR) != NULL) {
                 printf("%s", buffer);
        close (fds[0]);
                                                                    demo pipe.c
                                                                                   30
```

Summary

☐ A process is a program in execution OS maintains process info in PCB Process State diagram Creating and terminating processes (fork) ☐ Process scheduling Long-, short-, and medium-term schedulers Scheduling queues ☐ Interprocess communication Shared memory Message passing ☐ Threads Share memory between threads of a process Each thread executes independently