



# Linux Programming

# Topics

- 1) How can we do multitasking?
- 2) How can our multiple tasks communicate?
- 3) How can we communicate over the network?



# Concurrency: Processes & Threads

# Processes: fork() / exec\_\_()

- Each process has a separate..
- fork():...
- exec\_\_(): replaces current process with an executable file.

```
pid_t child_pid = fork();
if (child_pid != 0)
    printf ("Parent process: id %d\n", (int) getpid());
else {
    printf ("Child process: id %d\n", (int) getpid());

    // Exchange child for executing /bin/lis
    char *args[] = {"/bin/lis", "-l", "/dev/tty", (char *) 0};
    execv("/bin/lis", args);

    printf("Won't see this!\n");    ...

}
```

# Threads

- All threads of a process..

- Thread function:

```
void *myThreadFn(void *args)
{
    // Do stuff
    return NULL;
}
```

Direct access to  
shared (global)  
variables.

- Call:

```
- pthread_t id;
  pthread_create(&id, NULL, &myThreadFn, NULL);
```

Thread  
attributes

void\*  
Arguments

- Wait till thread finishes (and cleans up some memory):

```
- pthread_join(id, NULL);
```

- #include <pthread.h>

Can be void\*\* to  
hold return value  
from thread function

# Thread Synchronization

- Mutex:
  - Control access to critical sections.
  -
- Create:

```
pthread_mutex_t myMutex =  
    PTHREAD_MUTEX_INITIALIZER;
```
- Critical Section:

```
pthread_mutex_lock(&myMutex);  
{  
    // Do critical stuff here!  
}  
pthread_mutex_unlock(&myMutex);
```

# Thread considerations

- Tips for Critical Sections:
  - Keep critical sections short:  
avoid blocking other threads.
  - Calculate values with temporary variables;  
then update shared variables in critical section.
  - Use extra {...} to highlight the critical section.
  - Always unlock!
- Compiling (linking)  
`arm-linux-gnueabi-gcc -Wall -g demo_thread.c \`  
`-o demo_thread -pthread`

# Communicating Between Threads

- Code in different threads can interact in many ways
  - ..  
Use to signal events between threads.
  - ..  
Accessible between threads  
(but may need to be protected by critical sections).
  - .. (next)  
Can push data between threads or processes.



# Pipes

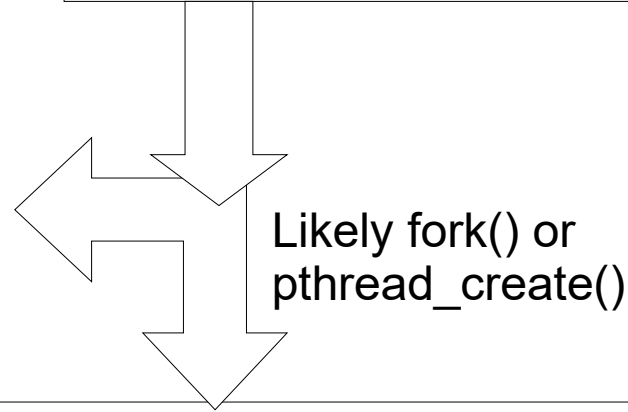
# Basics

- Pipe:
  - 
  - Good for inter-thread and inter-process communication.
- Needed Functions:
  - pipe() to create file descriptors for read and write ends of pipe.
  - fdopen() to open the pipe (from descriptor)
  - fprintf() to write (or other functions)
  - fgets() to read [blocking] (or other functions)
  - close() to close the file descriptor.

# Pipe Code

```
// Writer: Convert the write file descriptor
// to a FILE object
FILE* streamW = fdopen (fds[1], "w");
fprintf (streamW, "Hello World!\n");
fflush (streamW);
close (fds[1]);
```

```
// File descriptors for pipe ends
int fds[2];
// Create a pipe.
pipe (fds);
```



```
// Reader: Convert read file descriptor to a FILE object.
FILE* streamR = fdopen (fds[0], "r");
// Read until end of the stream.
char buffer[1024];
while (!feof (streamR) && !ferror (streamR)
      && fgets (buffer, sizeof (buffer), streamR) != NULL) {
    printf("%s", buffer);
}
close (fds[0]);
```

# popen() = Fork & pipe

- Execute a shell command using a pipe for output [or input].

```
#include <stdio.h>
#include <unistd.h>
#include <stdlib.h>
int main()
{
    // Execute the shell command (output into pipe)
    FILE *pipe = popen("ls -l /dev/tty*", "r");

    // Dump contents of pipe to the screen.
    char buffer[1024];
    while (!feof(pipe) && !ferror(pipe)) {
        if (fgets(buffer, sizeof(buffer), pipe) == NULL)
            break;
        printf("--> %s", buffer);
    }

    // Close pipe, check program's exit code
    int exitCode = WEXITSTATUS(pclose(pipe));
    if (exitCode != 0) {
        printf("program failed: %d\n", exitCode);
    }

    return 0;
}
```

# Sockets: Bidirectional network communication

I know a UDP joke, but I'm not sure you'll get it

# Socket Intro

- Socket
  - 
  - Used to send data between processes on the same computer, or across the network.
    - Like a pipe, but works across a network too.
- Use
  - Server:..
    - Usually at a known port number.
    - When data received, it knows client IP and port.
  - Client:..
    - May also wait for a reply.

# Socket Types

- Connection (TCP):
  - in order delivery, automatic retransmission
  - single connection between specific host and server.
  - Better for long term connections with large amount of data (fetch web-page).
- Datagram (UDP):
  - no persistent connection (connectionless):  
..
  - Better for short, single packet messages.
- See section 5.5 of Advanced Linux Programming for socket examples.

# UDP Server Programming (1/3 - Init)

- Address Structure

```
#define MAX_LEN 1024
```

```
#define PORT 22110
```

```
struct sockaddr_in sin;      // _in means internet
```

```
memset(&sin, 0, sizeof(sin));
```

```
sin.sin_family = AF_INET;    // Connection may be from network
```

```
sin.sin_addr.s_addr = htonl(INADDR_ANY);
```

```
sin.sin_port = htons(PORT);
```

```
// htonl = host to network long; htons = host to network short
```

- Create and bind to socket

```
int socketDescriptor = socket(PF_INET, SOCK_DGRAM, 0);
```

```
bind (socketDescriptor, (struct sockaddr*) &sin, sizeof(sin));
```

bind() really wants a sockaddr,  
but our sockaddr\_in is the right  
size and easier to use



# UDP Server Programming (2/3 - Read)

- Receive Data

```
struct sockaddr_in sinRemote;  
unsigned int sin_len = sizeof(sinRemote);  
char messageRx[MAX_LEN];  
int bytesRx = recvfrom(socketDescriptor,  
    messageRx, MAX_LEN - 1, 0,  
    (struct sockaddr *) &sinRemote, &sin_len);
```

Client's data written  
into messageRx string

sinRemote is output parameter;  
sinLen is in/out parameter.  
..

```
// Null terminated (string):  
messageRx[bytesRx] = 0;
```

... What if recvfrom filled the  
buffer 100%? Overflow?

```
printf("Message received (%d bytes): '%s'\n",  
    bytesRx, messageRx);
```

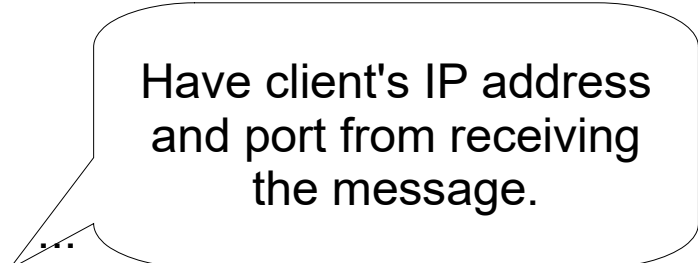
# UDP Socket Programming (3/3 Reply)

- Create Reply

```
// Watch for buffer overflow!  
char messageTx[MAX_LEN];  
sprintf(messageTx, "Hello %d\n", 42);
```

- Send Reply

```
sin_len = sizeof(sinRemote);  
sendto( socketDescriptor,  
        messageTx, strlen(messageTx),  
        0,  
        (struct sockaddr *) &sinRemote, sin_len);
```



Have client's IP address  
and port from receiving  
the message.

- Close socket (when done)

```
close(socketDescriptor);
```

- May take a few seconds for OS to finish closing.

# Byte Order

- - 2 bytes of 0xa1cf transmitted as 0xa1, 0xcf
  - Big-endian = network byte order...
  - x86 is little-endian; ARM is bi-endian (supports both)
- Never assume your processor is network order:  
use host-to-network to adjust:

## Prototypes

```
uint32_t htonl(uint32_t hostlong);  
uint16_t htons(uint16_t hostshort);  
uint32_t ntohl(uint32_t netlong);  
uint16_t ntohs(uint16_t netshort);
```

## Example

```
#include <netdb.h>
```

```
short toTransmit1 = htons(myVal1);  
long toTransmit2 = htonl(myVal2);
```

# Summary

- Use processes for coarse multitasking:
  - Use `fork()` and `exec__()`.
  - Example: A server and a client with well defined separate roles.
- Use threads for fine-grained multitasking.
  - Use `pthread_create()`, `pthread_join`
  - Mutex with `pthread_mutex_t`: `pthread_mutex_lock()`, `pthread_mutex_unlock()`.
- Pipes for inter process/thread communication.
- Sockets for network communication.