



# Linux Programming

# Topics

- 1) How can we do **multitasking**?
- 2) How can our **multiple tasks communicate**?
- 3) How can we **communicate** over the **network**?



# Concurrency: Processes & Threads

# Processes: fork() / exec\_\_()

- Each process has a separate..
- `fork():..`
- `exec__()`: replaces current process with an executable file.

```
pid_t child_pid = fork();
if (child_pid != 0)
    printf ("Parent process: id %d\n", (int) getpid());
else {
    printf ("Child process: id %d\n", (int) getpid());

    // Exchange child for executing /bin/lS
    char *args[] = {"/bin/lS", "-l", "/dev/tty", (char *) 0};
    execv("/bin/lS", args);

    printf("Won't see this!\n");    ...
}
```

# Threads

- All threads of a process..

- Thread function:

```
void *myThreadFn(void *args)
{
    // Do stuff
    return NULL;
}
```

Direct access to shared (global) variables.

- Call:

```
- pthread_t id;
  pthread_create(&id, NULL, &myThreadFn, NULL);
```

Thread attributes

void\* Arguments

- Wait till thread finishes (and cleans up some memory):

```
- pthread_join(id, NULL);
```

- #include <pthread.h>

Can be void\*\* to hold return value from thread function

# Thread Synchronization

- **Mutex:**

- Control access to critical sections.
- 

- **Create:**

```
pthread_mutex_t myMutex =  
    PTHREAD_MUTEX_INITIALIZER;
```

- **Critical Section:**

```
pthread_mutex_lock(&myMutex);  
{  
    // Do critical stuff here!  
}  
pthread_mutex_unlock(&myMutex);
```

# Thread considerations

- **Tips for Critical Sections:**

- Keep critical sections short: avoid blocking other threads.
- Calculate values with temporary variables; then update shared variables in critical section.
- Use extra {...} to highlight the critical section.
- Always unlock!

- **Compiling (linking)**

```
arm-linux-gnueabi-gcc -Wall -g demo_thread.c \  
-o demo_thread -pthread
```

# Communicating Between Threads

- Code in different threads can interact in many ways
  - ..  
Use to signal events between threads.
  - ..  
Accessible between threads  
(but may need to be protected by critical sections).
  - .. (next)  
Can push data between threads or processes.

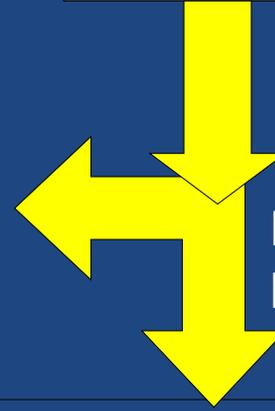
# Pipes

- **Pipe:**
  - 
  - Good for inter-thread and inter-process communication.
- **Needed Functions:**
  - **pipe()** to create file descriptors for read and write ends of pipe.
  - **fdopen()** to open the pipe (from descriptor)
  - **fprintf()** to write (or other functions)
  - **fgets()** to read [blocking] (or other functions)
  - **close()** to close the file descriptor.

# Pipe Code

```
// Writer: Convert the write file descriptor  
// to a FILE object  
FILE* streamW = fdopen (fds[1], "w");  
fprintf (streamW, "Hello World!\n");  
fflush (streamW);  
close (fds[1]);
```

```
// File descriptors for pipe ends  
int fds[2];  
// Create a pipe.  
pipe (fds);
```



Likely fork() or  
pthread\_create()

```
// Reader: Convert read file descriptor to a FILE object.  
FILE* streamR = fdopen (fds[0], "r");  
// Read until end of the stream.  
char buffer[1024];  
while (!feof (streamR) && !ferror (streamR)  
      && fgets (buffer, sizeof (buffer), streamR) != NULL) {  
    printf("%s", buffer);  
}  
close (fds[0]);
```

# popen() = Fork & pipe

- Execute a shell command using a pipe for output [or input].

```
#include <stdio.h>
#include <unistd.h>
#include <stdlib.h>
int main()
{
    // Execute the shell command (output into pipe)
    FILE *pipe = popen("ls -l /dev/tty*", "r");

    // Dump contents of pipe to the screen.
    char buffer[1024];
    while (!feof(pipe) && !ferror(pipe)) {
        if (fgets(buffer, sizeof(buffer), pipe) == NULL)
            break;
        printf("--> %s", buffer);
    }

    // Close pipe, check program's exit code
    int exitCode = WEXITSTATUS(pclose(pipe));
    if (exitCode != 0) {
        printf("program failed: %d\n", exitCode);
    }

    return 0;
}
```

# Sockets: Bidirectional network communication

I know a UDP joke, but I'm not sure you'll get it

# Socket Intro

- **Socket**
  - 
  - Used to send data between processes on the same computer, or across the network.
    - Like a pipe, but works across a network too.
- **Use**
  - **Server:...**
    - Usually at a known port number.
    - When data received, it knows client IP and port.
  - **Client:...**
    - May also wait for a reply.

# Socket Types

- **Connection (TCP):**
  - in order delivery, automatic retransmission
  - single connection between specific host and server.
  - Better for long term connections with large amount of data (fetch web-page).
- **Datagram (UDP):**
  - no persistent connection (connectionless):  
..
  - Better for short, single packet messages.
- See section 5.5 of *Advanced Linux Programming* for socket examples.

# UDP Server Programming (1/3 - Init)

- **Address Structure**

```
#define MAX_LEN 1024
#define PORT 22110

struct sockaddr_in sin; // _in means internet
memset(&sin, 0, sizeof(sin));
sin.sin_family = AF_INET; // Connection may be from network
sin.sin_addr.s_addr = htonl(INADDR_ANY);
sin.sin_port = htons(PORT);
// htonl = host to network long; htons = host to network short
```

- **Create and bind to socket**

```
int socketDescriptor = socket(PF_INET, SOCK_DGRAM, 0);
bind (socketDescriptor, (struct sockaddr*) &sin, sizeof(sin));
```

bind() really wants a sockaddr,  
but our sockaddr\_in is the right  
size and easier to use

# UDP Server Programming (2/3 - Read)

- **Receive Data**

```
struct sockaddr_in sinRemote;  
unsigned int sin_len = sizeof(sinRemote);  
char messageRx[MAX_LEN];
```

```
int bytesRx = recvfrom(socketDescriptor,  
messageRx, MAX_LEN - 1, 0,  
(struct sockaddr *) &sinRemote, &sin_len);
```

Client's data written into `messageRx` string

`sinRemote` is output parameter;  
`sinLen` is in/out parameter.

```
// Null terminated (string):  
messageRx[bytesRx] = 0;
```

... What if `recvfrom` filled the buffer 100%? Overflow?

```
printf("Message received (%d bytes): '%s'\n",  
bytesRx, messageRx);
```

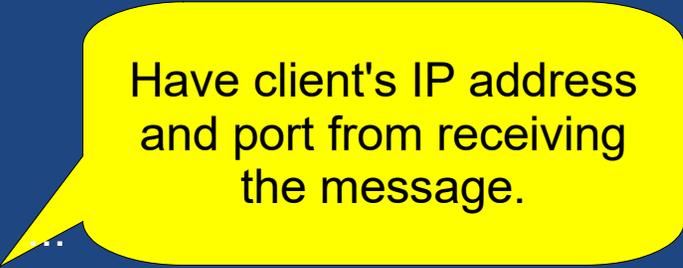
# UDP Socket Programming (3/3 Reply)

- **Create Reply**

```
// Watch for buffer overflow!  
char messageTx[MAX_LEN];  
sprintf(messageTx, "Hello %d\n", 42);
```

- **Send Reply**

```
sin_len = sizeof(sinRemote);  
sendto( socketDescriptor,  
        messageTx, strlen(messageTx),  
        0,  
        (struct sockaddr *) &sinRemote, sin_len);
```



Have client's IP address  
and port from receiving  
the message.

- **Close socket (when done)**

```
close(socketDescriptor);
```

- May take a few seconds for OS to finish closing.

# Byte Order

- - 2 bytes of **0xa1cf** transmitted as **0xa1**, **0xcf**
  - **Big-endian** = network byte order:..
  - x86 is little-endian; ARM is bi-endian (supports both)
- Never assume your processor is network order:  
use **host-to-network** to adjust:

## Prototypes

```
uint32_t htonl(uint32_t hostlong);  
uint16_t htons(uint16_t hostshort);  
uint32_t ntohl(uint32_t netlong);  
uint16_t ntohs(uint16_t netshort);
```

## Example

```
#include <netdb.h>
```

```
short toTransmit1 = htons(myVal1);  
long toTransmit2 = htonl(myVal2);
```

# Summary

- Use **processes** for coarse multitasking:
  - Use **fork()** and **exec\_\_()**.
  - Example: A server and a client with well defined separate roles.
- Use **threads** for fine-grained multitasking.
  - Use **pthread\_create()**, **pthread\_join**
  - Mutex with **pthread\_mutex\_t**: **pthread\_mutex\_lock()**, **pthread\_mutex\_unlock()**.
- **Pipes** for inter process/thread communication.
- **Sockets** for network communication.