

Synchronization: Intro & Mutex



CMPT 201

Slides 8.1

Based on content
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Topics

- How can we prevent two threads from having a race case?
- How can we code a mutex in C?
- What's important to get right about locks?

- Synchronization

- ..

- Careful synchronization avoids difficult to debug race cases.

- Race cases are *hard* because:

- ..

- ..

- not just single path's correctness.

- We'll learn synchronization primitives:

- locks (mutex)

- condition variables (next slide deck)

- semaphores (next slide deck)

Details

- Can find more info in OSTEP book
(more depth than we require)
 - Chapter 28 Locks
<https://pages.cs.wisc.edu/~remzi/OSTEP/threads-locks.pdf>
 - Chapter 30 Condition Variables
<https://pages.cs.wisc.edu/~remzi/OSTEP/threads-cv.pdf>
 - Chapter 31 Semaphores
<https://pages.cs.wisc.edu/~remzi/OSTEP/threads-sema.pdf>
 - Chapter 32 Concurrency Bugs
<https://pages.cs.wisc.edu/~remzi/OSTEP/threads-bugs.pdf>

Locks: Mutexes

Motivation

- Recall race case from Threads notes (assume counter = 5):

Thread 1	Thread 2
int tmp1 = counter	
tmp1++	
counter = tmp1	= 6
	int tmp2 = counter
	tmp2++
	counter = tmp2
	= 7

Thread 1	Thread 2
int tmp1 = counter	
	int tmp2 = counter
tmp1++	
	tmp2++
counter = tmp1	
= 6	counter = tmp2
	= 6

- What looks like one operation

..

- We need to prevent this mix-up of sub-operations from different threads.
- Use a lock or a **mutex**: ..

Locks

- Lock mechanisms consists of:
 - ..
 - .. function that grabs a lock
 - .. function that releases a lock
- E.g.: pthread library's lock:
 - Define lock:
`pthread_mutex_t myLock = PTHREAD_MUTEX_INITIALIZER;`
 - Mutex lock function:
`int pthread_mutex_lock(pthread_mutex_t *mutex)`
 - Mutex unlock function:
`int pthread_mutex_unlock(pthread_mutex_t *mutex)`

Other languages (e.g., Java, Python, etc.)
have similar lock mechanisms.

pthread Example

- Locks guarantee: ..

```
static pthread_mutex_t data_mutex = PTHREAD_MUTEX_INITIALIZER;
static int data[10];

static void *thread0(void *arg) {
    int count = 0;

    pthread_mutex_lock(&data_mutex);
    {
        for (int i = 0; i < 10; i++) {
            count += data[i];
        }
        pthread_mutex_unlock(&data_mutex);
        printf("Sum is %d\n", count);
        pthread_exit(0);
    }
}

static void *thread1(void *arg) {
    pthread_mutex_lock(&data_mutex);
    {
        for (int i = 0; i < 10; i++) {
            data[i] += 1;
        }
        pthread_mutex_unlock(&data_mutex);
        printf("Done update!\n");
        pthread_exit(0);
    }
}
```

T0 locks mutex

T1 tries to lock mutex

T0 access data[]

T0 unlocks mutex. This unblocks T1

Operation of Lock

- `pthread_mutex_lock(&mutex)` either:
 - a) ..
 - b) ..
- **Mutual Exclusion**
 - Even if multiple threads call `lock()` at once,
..
all other threads wait
 - We cannot control the order in which threads grab the lock.
It depends on the underlying lock mechanism.
- **Non-deterministic**
 - This behaviour is **non-deterministic**:
..
 - Opposite of **deterministic** behaviour.

ABCD: Code with Data Race

```
int cnt = 0;

static void *thread_func(void *arg) {
    for (int i = 0; i < 10000000; i++)
        cnt++;
    pthread_exit(0);
}

int main(int argc, char *argv[]) {
    pthread_t t1;
    pthread_t t2;

    pthread_create(&t1, NULL, thread_func, NULL);
    pthread_create(&t2, NULL, thread_func, NULL);

    pthread_join(t1, NULL);
    pthread_join(t2, NULL);

    printf("%d\n", cnt);

    exit(EXIT_SUCCESS);
}
```

This code suffers a data race.

What is the cause of this data race?

- a) T2 may start before T1
- b) T2 may end before T1
- c) T1 and T2 share cnt
- d) T1 and T2 share i

Code with error checking

```
int cnt = 0;

static void *thread_func(void *arg) {
    for (int i = 0; i < 10000000; i++)
        cnt++;
    pthread_exit(0);
}

int main(int argc, char *argv[]) {
    pthread_t t1;
    pthread_t t2;

    if (pthread_create(&t1, NULL, thread_func, NULL) != 0)
        perror("pthread_create");

    if (pthread_create(&t2, NULL, thread_func, NULL) != 0)
        perror("pthread_create");

    if (pthread_join(t1, NULL) != 0)
        perror("pthread_join");
    if (pthread_join(t2, NULL) != 0)
        perror("pthread_join");

    printf("%d\n", cnt);
    exit(EXIT_SUCCESS);
}
```

This is the same code as previous slide, but shows error checking on functions.

You should do this!
(Slides omit for brevity)

Mutex Protected

```
int cnt = 0;
pthread_mutex_t mutex = PTHREAD_MUTEX_INITIALIZER;

static void *thread_func(void *arg) {
    for (int i = 0; i < 10000000; i++) {
        pthread_mutex_lock(&mutex);
        cnt++;
        pthread_mutex_unlock(&mutex);
    }
    pthread_exit(0);
}

int main(int argc, char *argv[]) {
    pthread_t t1;
    pthread_t t2;

    pthread_create(&t1, NULL, thread_func, NULL);
    pthread_create(&t2, NULL, thread_func, NULL);

    pthread_join(t1, NULL);
    pthread_join(t2, NULL);

    printf("%d\n", cnt);
    exit(EXIT_SUCCESS);
}
```

- Protect the critical section with a lock.
- A thread trying to change `cnt` must do so with mutex locked.
- `man pthread_mutex_lock`
- Why not lock outside the loop?

Lock Usage

Atomicity

- **Atomicity**
 - Atomic:
 - ..
 - Cannot be interfered with by other sections with same lock.
 - Mutex lock makes a section of code atomic.
 - **Atomicity**: **all or nothing** as it runs either all operations or no operations at all.
- **Serialization and interleaving**
 - Lock effectively serializes operations:
 - ..
 - Operations from different threads are interleaved in some order.
We *cannot* control the order in which different threads run.

Protecting shared variables

- Can have a data race when threads share a variable
 - e.g. Accessing same.. `cnt++`
 - e.g. Accessing same..
`pSharedBuffer[i] = 52;`
- Solve data race with a lock
 - Controls and serializes access to shared variable
- Where in the code?
 - Data race may be..
e.g.: One function called by multiple threads
tracking next free block to allocate.
 - May be in..

thread fills buffer, one thread empties buffer.

Multiple locks

- Can have multiple locks

..

- e.g. A system might have:
 - `data_samples_mutex`
 - `printer_mutex`
- Each code section / thread locks the mutex(es) it needs to lock be safe.
- Reducing..
is important for performance to allow multiple parallel operations.

Non-Blocking Lock

- Options to allow us to control blocking behaviour:
 - `pthread_mutex_trylock()`
..
 - `pthread_mutex_timedlock()`
waits a maximum amount of time before returning if unable to lock.

Critical Section (CS) and Thread Safety

Critical Section (CS)

- **Critical Section:**
A critical section is a piece of code that
..
(or more generally, a shared resource) and
..
-- From OSTEP
- **Rephrased:**
 - If a thread is executing the CS,
no other threads should execute the CS.

Critical Section (CS)

- An ideal solution for CS problem must satisfy 3 requirements:
 - Mutual exclusion
 - ..
 - Progress
 - ..
 - Bounded waiting
 - ..

i.e., a thread should only be blocked for a finite amount of time.

Thread safety & Reentrant

- Thread safe function

..

It either:

- a) does not access shared resources or
- b) provides proper protection for CS that access shared resources.

- Reentrant vs nonreentrant functions (related concept)

- A reentrant function is a function that
 - ..
- Must work with different threads (thread safe), and also
 - ..
- i.e., a function called by `main()` might also be called by a signal handler on the same thread.

ABCD: Thread safety (1)

a) Thread safe: YES	Reentrant YES
b) Thread safe: YES	Reentrant NO
c) Thread safe: NO	Reentrant YES
d) Thread safe: NO	Reentrant NO

- How thread safe is this function?

```
int tmp = 0;

int swap(int *pA, int *pB) {
    tmp = *pA;
    *pA = *pB;
    *pB = tmp;
}
```

ABCD: Thread safety (2)

a) Thread safe: YES	Reentrant YES
b) Thread safe: YES	Reentrant NO
c) Thread safe: NO	Reentrant YES
d) Thread safe: NO	Reentrant NO

- How thread safe is this function?

```
int tmp = 0;
pthread_mutex_t mutex = PTHREAD_MUTEX_INITIALIZER;

int swap(int *pA, int *pB) {
    pthread_mutex_lock(&mutex);
    tmp = *pA;
    *pA = *pB;
    *pB = tmp;
    pthread_mutex_unlock(&mutex);
}
```

ABCD: Thread safety (3)

a) Thread safe: YES	Reentrant YES
b) Thread safe: YES	Reentrant NO
c) Thread safe: NO	Reentrant YES
d) Thread safe: NO	Reentrant NO

- How thread safe is this function?

```
int swap(int *pA, int *pB) {  
    int tmp = 0;  
  
    tmp = *pA;  
    *pA = *pB;  
    *pB = tmp;  
  
}
```

Making Functions Reentrant

- A function might work with some data, like a buffer:
 - use a shared global buffer
 - use a shared thread-local buffer
- Possible Reentrant Solutions:
 - allocate its own local variable buffer on the stack
 - dynamically allocate and free new buffer in the heap
 - have calling code allocate space and pass it in
- Caller Allocates Technique
 - Many functions make the calling code pass in the buffer.
e.g., `strtok_r()`
 - ..

Deadlock and Livelock

Deadlock

- **Deadlock**
a condition where a set of threads
..
 - The threads get stuck and make no progress.
- **E.g.:**
 - Create mutex locks **A** & **B**
 - **Thread 1**: locks **A**
 - **Thread 2**: locks **B**, then blocks trying to lock **A**
 - **Thread 1**: blocks trying to lock **B**

Deadlock Activity

- [15 min]

Write a program that creates two threads and two locks:

Thread #0:

Lock A
Print
Lock B
Print
Unlock B
Unlock A
Print

Thread #1:

Lock B
Print
Lock A
Print
Unlock A
Unlock B
Print

Useful Thread Code

```
#include <pthread.h>
static void *func(void *arg) {
    pthread_exit(0);
}

int main(int argc, char *argv[]) {
    pthread_t t1;

    pthread_create(&t1, NULL, func, NULL);

    pthread_join(t1, NULL);
}
```

- Investigation

- Does it *always* finish (run multiple times)?
- Does it *always* not finish (run multiple times)?
- What happens if both threads lock A and B in the same order?

Necessary Conditions for Deadlock

- 4 conditions are necessary for deadlock:

These do not guarantee deadlock:
deadlock also depends on timing of thread execution.

1) Hold and wait:

..

2) ..

there exists a set $\{T_0, T_1, \dots, T_{n-1}\}$ of threads such that
T0 is waiting for a resource that is held by T1,
T1 is waiting for T2, ..., T_{n-1} is waiting for T0.

3) Mutual exclusion:

..

4) No preemption:

resource released only voluntarily by the thread holding it

Apply Deadlock Conditions

- E.g.: Thread 1

```
Lock A
Print
Lock B
Print
Unlock B
Unlock A
Print
```

- Thread 2

```
Lock B
Print
Lock A
Print
Unlock A
Unlock B
Print
```

- 4 Conditions to Check

- Hold and wait?
- Circular wait?
- Mutual Exclusion?
- No preemption?

All 4 conditions hold.
Therefore, it's
POSSIBLE to have
deadlock.

- Deadlock Prevention

- Break one of these for conditions to prevent deadlocks.

Preventing Deadlocks

- Technique 1:..

- ..

you grab all the locks together or no locks at all

```
static pthread_mutex_t mutex0 = PTHREAD_MUTEX_INITIALIZER;
static pthread_mutex_t mutex1 = PTHREAD_MUTEX_INITIALIZER;
static pthread_mutex_t another_lock = PTHREAD_MUTEX_INITIALIZER;

static void *thread0(void *arg) {
    pthread_mutex_lock(&another_lock);
    {
        pthread_mutex_lock(&mutex0);
        printf("thread0: mutex0\n");
        pthread_mutex_lock(&mutex1);
    }
    pthread_mutex_unlock(&another_lock);

    printf("thread0: mutex1\n");
    pthread_mutex_unlock(&mutex1);
    pthread_mutex_unlock(&mutex0);
    pthread_exit(0);
}

static void *thread1(void *arg) {
    pthread_mutex_lock(&another_lock);
    {
        pthread_mutex_lock(&mutex1);
        printf("thread1: mutex1\n");
        pthread_mutex_lock(&mutex0);
    }
    pthread_mutex_unlock(&another_lock);

    printf("thread1: mutex0\n");
    pthread_mutex_unlock(&mutex0);
    pthread_mutex_unlock(&mutex1);
    pthread_exit(0);
}
```

Preventing Deadlocks

- **Technique 2:..**
 - Acquiring locks in the same global order for all threads:
..
as all threads try to grab locks in the exact same order.

```
static pthread_mutex_t mutex0 = PTHREAD_MUTEX_INITIALIZER;  
static pthread_mutex_t mutex1 = PTHREAD_MUTEX_INITIALIZER;
```

```
static void *thread0(void *arg) {  
    pthread_mutex_lock(&mutex0);  
    printf("thread0: mutex0\n");  
  
    pthread_mutex_lock(&mutex1);  
    printf("thread0: mutex1\n");  
  
    pthread_mutex_unlock(&mutex1);  
    pthread_mutex_unlock(&mutex0);  
    pthread_exit(0);  
}
```

```
static void *thread1(void *arg) {  
    pthread_mutex_lock(&mutex0);  
    printf("thread1: mutex0\n");  
  
    pthread_mutex_lock(&mutex1);  
    printf("thread1: mutex1\n");  
  
    pthread_mutex_unlock(&mutex1);  
    pthread_mutex_unlock(&mutex0);  
    pthread_exit(0);  
}
```

Livelock

- **Livelock:**
where a set of threads each execute instructions actively, but..
- **E.g.: Threads T0 and T1**
Each attempts to acquire two resources R0 and R1

```
while (true)
  Acquire R0
  if R1 is free, then
    Acquire R1
    do work
    Free R1, R0
    return
  else
    Free R0
```

```
while (true)
  Acquire R1
  if R0 is free, then
    Acquire R0
    do work
    Free R0, R1
    return
  else
    Free R1
```

- **Problem:** T0 and T1 run concurrently:
..
- Each frees first resource, and then tries again forever.

Livelock vs Deadlock

```
while (true)
  Acquire R0
  if R1 is free, then
    Acquire R1
    do work
    Free R1, R0
    return
  else
    Free R0
```

```
while (true)
  Acquire R1
  if R0 is free, then
    Acquire R0
    do work
    Free R0, R1
    return
  else
    Free R1
```

- **Livelock:**
Thread 0 and Thread 1 actively execute code but do not make any progress.
- **Deadlock vs Livelock**
 - Both deadlocks and livelocks do not make any progress. In a livelock scenario, threads do still execute.
 - In a deadlock scenario,
..

ABCD: Identify the problem

- What synchronization problem is present in this code with two functions if they are called from different threads, and where **M0** and **M1** are mutexes.

```
global int cnt = 0;

foo():
    while (true):
        lock M0

        if cnt % 2 == 1 then:
            lock M1
            cnt++
            unlock M1

        unlock M0

bar():
    while (true):
        lock M0

        if cnt % 2 == 0 then:
            lock M1
            cnt++
            unlock M1

        unlock M0
```

- a) Race case
- b) Non-reentrant
- c) Livelock
- d) Deadlock

Summary

- **Mutex**
 - Used for **Mutual Exclusion** from a critical section.
 - Guarantees only one thread can hold the lock
- **Critical Section**
 - Area of the code which accesses a **shared variable** that **must not be concurrently accessed** from another thread.
- **Thread safe**: Correctly runs with multiple threads.
- **Reentrant**: Correctly runs when called again while running (same thread?)
- **Deadlock**: Two threads blocking each other. Necessary conditions:
 - **Hold and wait**
 - **Circular wait**
 - **Mutual exclusion**
 - **No preemption**