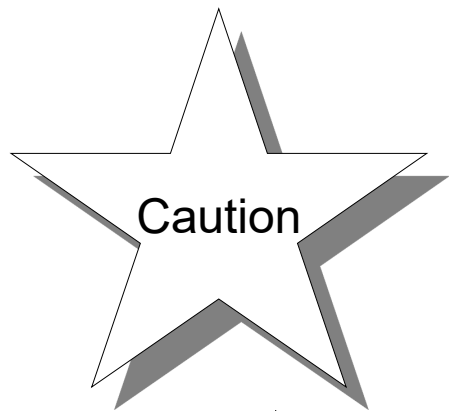


Intro to Linux Kernel



Kernel coding is different!

Can be hard to understand
different syntax, functions,
advanced C code in kernel!

Topics

- 1) How can we see an application's sys-calls?
- 2) How does Linux kernel work with hardware?
- 3) How do we build and load a kernel image?



strace:
Viewport to the Kernel

Accelerometer Motivation Demo

- See Accelerometer Data Sheet: p22 for who-am-i register
 - I2C address 0x1C
 - Who-am-i Register 0x0D

- Setup

```
(bbg) $ config-pin p9_18 i2c
(bbg) $ config-pin p9_17 i2c
(bbg) $ i2cdetect -l
(bbg) $ i2cdetect -y -r 1
```

- Run i2cget

```
(bbg) $ i2cget -y 1 0x1C 0x0D
= 0x2a
```

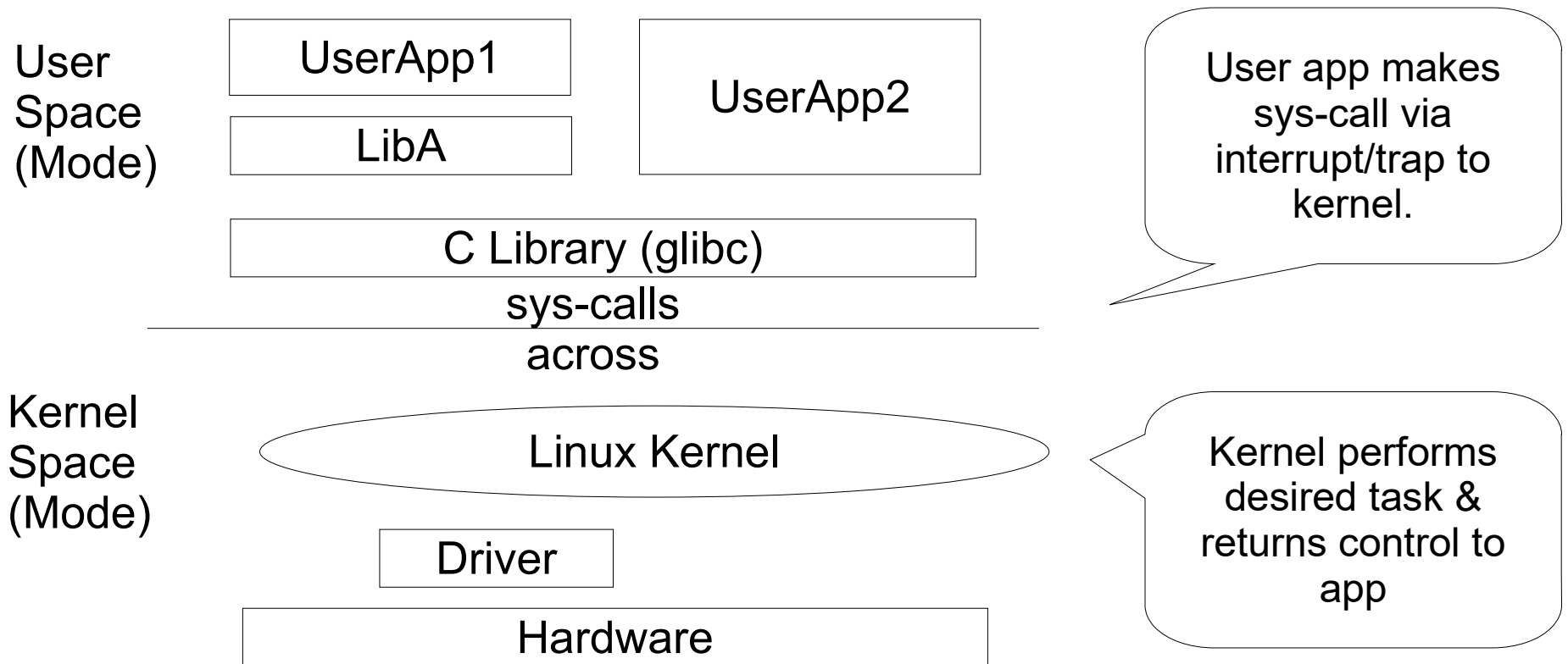
- Run my tool

```
(bbg) $ ./myi2cget
= 0x??
```

?!? Why ?!?

What is i2cget doing
that it works?
Let's find out!

User vs Kernel Space (“Mode”)



- Kernel is..
 - ..
 - Errors in user application don't crash system.

strace

- strace: ..
 - “**Sys-call trace**”
 - Command:
(bbg)\$ strace ./myApp some args 2> outputFile.txt
 - 2> redirects stderr to a file
- strace Output format
`sysCallFunction(args, ...)` = ReturnValue

ioctl()

```
debian@beaglebone:/dev$ ls -l ttyS*  
crw----- 1 debian tty    4, 64 Mar  1 2021 ttyS0  
crw-rw---- 1 root  dialout 4, 65 Feb 27 06:57 ttyS1  
crw-rw---- 1 root  dialout 4, 66 Feb 27 06:57 ttyS2
```

- Device Nodes in /dev

```
(bbg) $ ls -l /dev
```

- c = character, b = block

- Node #'s (before date):

- major = which driver; minor = sub-part of driver

- ioctl()..

- Arguments

1. File descriptor

2. Device-dependent request code

3. void* or an unsigned long
(dependent on request code)

I2C strace Demo

- Run strace
 - (bbg)\$ sudo apt-get install strace
 - (bbg)\$ cd /mnt/remote/myApps
 - (bbg)\$ **strace ./myi2cget 2> myi2cget.txt**
 - (bbg)\$ **strace i2cget -y 1 0x1C 0x0D 2> i2cget.txt**

- Look at myi2cget.txt

```
open("/dev/i2c-1", O_RDWR)           = 3
ioctl(3, 0x703, 0x1c)                 = 0
write(3, "\r", 1)                     = 1
read(3, "\0", 1)                      = 1
close(3)                              = 0
```


I2C strace Demo Analysis

myi2cget.txt

```
open("/dev/i2c-1", O_RDWR) = 3
```

```
ioctl(3, 0x703, 0x1c) = 0  
Set Slave Mode
```

```
write(3, "\r", 1) = 1  
Set reg addr: '\r' = 0x0d
```

```
read(3, "\0", 1) = 1  
Read 1 byte
```

```
close(3) = 0
```

i2cget.txt

```
open("/dev/i2c-1", O_RDWR) = 3  
ioctl(3, 0x705, 0xbe8f5b50) = 0  
Get capabilities; 2nd arg is  
*long
```

```
ioctl(3, 0x703, 0x1c) = 0  
Set Slave Mode
```

```
ioctl(3, 0x720, 0xbe8f5b50) = 0  
SMBUS operations (pass pointer)
```

```
close(3) = 0
```

0x720?

Following I2C_SLAVE into i2c-dev.h
0x720
= I2C_SMBUS (system management bus)
= protocol built on top of I2C
So, we're using I2C, i2cget uses SMBus

Linux Kernel Basics

Kernel Basics

- Monolithic kernel
 - ..
 - fully linked (no run-time dependencies)
 - no fool-proof internal memory protection
- Kernel source directory structure
 - Documentation/ - Kernel docs (Ex: coding style guide)
 - include/ - Kernel header files
 - drivers/ - Source code to drivers
 - .../char/ - Byte-based drivers
 - arch/arm/ - ARM specific code
 - init/ - General startup code

Drivers

- ..
- Types of Drivers
 - Packet: Networks
 - Block: Disk and memory
 - Character: ..
Ex: tty, input, console, frame buffer, sound, ...
- Can compile module into the kernel image
 - good for network, file-system, etc.
- Can compile driver into a..
 - Compiled for kernel's internal interface (functions)
-- specific to a kernel version
 - Creates a .ko file: Kernel Object; in /lib/modules/...

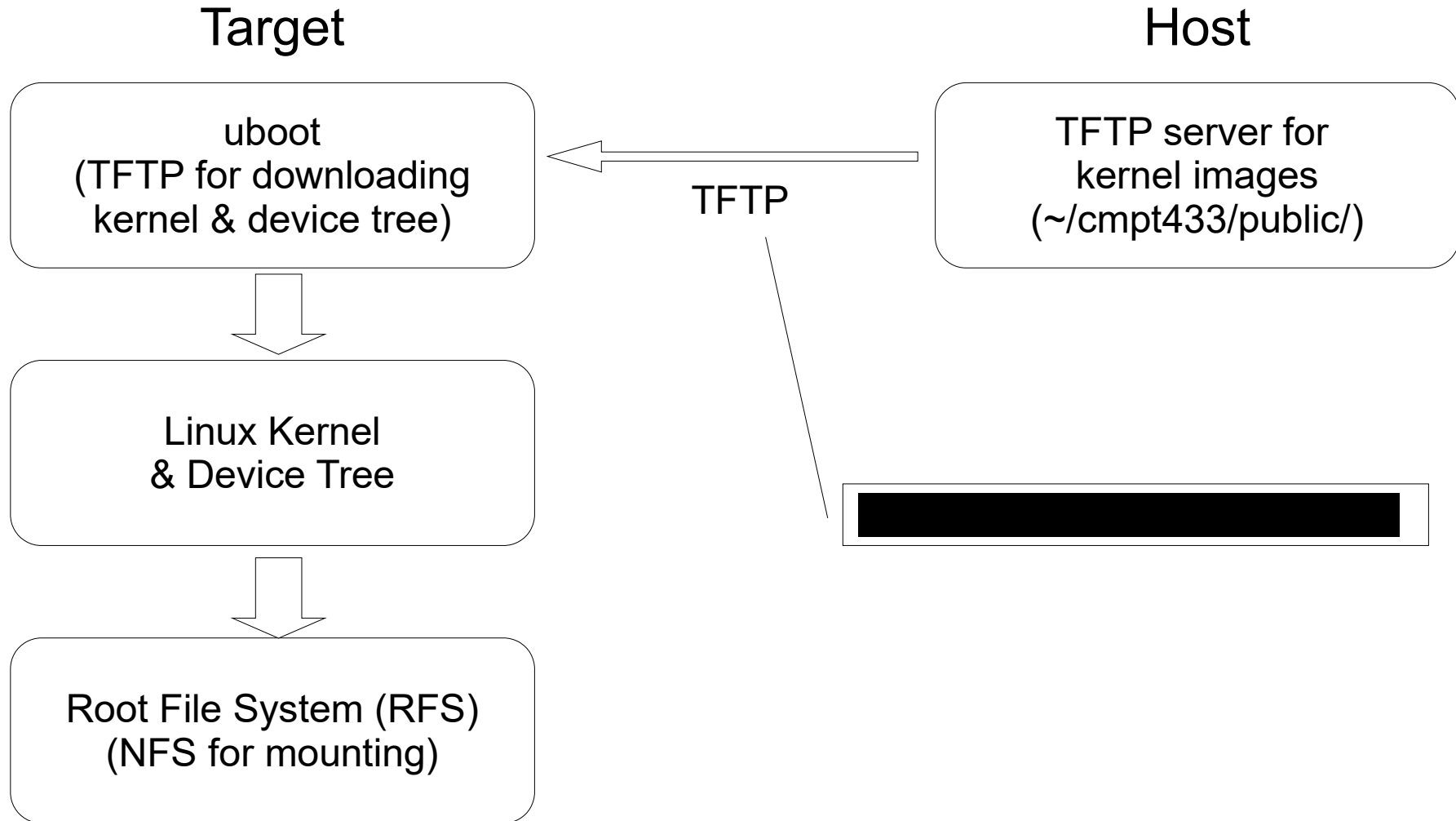
How Kernel knows Hardware

- Kernel must be told about the hardware in product
 - Many embedded board configurations!
 - "Old" way: board specific headers with hardware info:
 - serial ports, memory size, peripheral addresses, ...
- Problem?
 - Every new board/change requires push of code into Linux kernel.
 - Maintainers getting inundated with pushes (Linus rant)
- Solution: (Kernel 3.8+)
 - Create a special file to store hardware description
=..

Device Tree

- Device Tree..
 - Kernel needs this to provide services.
Ex:
 - What serial ports are connected?
 - What LEDs are connected? Where?
- Device Tree's File Types
 - .dts:..
in arch/arm/boot/dts
 - .dtb:..
Passed to kernel via U-Boot
 - .dtbo:..
Change the device tree at runtime

Boot Sequence if Downloading new Kernel



Summary & Demo

- strace: view app's sys-calls
- Kernel drivers (“modules”)
 - run-time loadable or compiled into kernel image
- Device Tree: config file describing the hardware
- Boot Sequence
 - uboot: download kernel and device tree
 - run Linux & device tree
 - Loads root file system
- **DEMO:**
 - Kernel build, download & boot demo.
 - See Driver Creation Guide for details.