

SPI (Serial Peripheral Interface) Guide for BeagleY-AI

by Brian Fraser

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Guide has been tested on

BeagleY-AI (Target): **Debian 12.8** (bit it's version independent)

PC OS (host): **Debian 12.8** (or higher)

This document guides the user through

1. Setting up the hardware SPI

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Formatting

1. Commands for the host Linux's console are show as:
`(host)$ echo "Hello PC world!"`
2. Commands for the target (BeagleY-AI) Linux's console are shown as:
`(byai)$ echo "Hello embedded world!"`

Revision History

- Mar 31, 2025: Target the Beagle-Y AI

1. SPI

The LCD on the Zen Hat is connected via the Serial Peripheral Interface (SPI). It is a four wire protocol:

- Serial Clock (`SCLK`): This is the clock that controls when data is transmitted.
- Master Out, Slave In (`MOSI`): Transmits data from the CPU to the LCD
- Master In, Slave out (`MISO`): Transmits data from the device back to the CPU. This is not used for the LCD because it sends no data to the CPU.
- Chip Enable (`CE`): Also called chip select, or device enable. This allows multiple devices to share the same SPI bus. In this case, `CE0` is wired to the LCD. `CE1` is connected to the `PYMNL` headre on the Zen Hat and can be connected to a different SPI device so that it shares the same `SCLK`, `MOSI`, and `MISO` wires (also on the `PYMNL` header).

This guide is heavily based on the [a guide produced by William Schmidt](#) (student in CMPT 433, Spring 2025). Thanks William!

1. On the target, copy the device tree source files to your home directory:
 - Check your installed kernel version

```
(byai)$ uname -r
6.1.83-ti-arm64-r63
```
 - List the Device Tree source versions installed on the target:

```
(byai)$ ls -dl /opt/source/dtb*
/opt/source/dtb-5.10-ti
/opt/source/dtb-6.1-Beagle
/opt/source/dtb-6.6-Beagle
/opt/source/dtb-6.9
```
 - Copy the device tree source folder which matches your kernel to your home directory so we can modify it. In my case, it's 6.1:

```
(byai)$ cp -R /opt/source/dtb-6.1-Beagle ~
```
2. Clone William Schmidt's SPI device tree file which supports the MCU SPI (hardware):

```
(byai)$ cd ~
(byai)$ git clone https://github.com/wcs3/BYAI-mcu_spi0.git
```

 - You will need internet access to do this.
3. Copy the new device tree into the device tree source folder:

```
(byai)$ cd ~/dtb-6.1-Beagle/src/arm64/overlays/
(byai)$ cp ~/BYAI-mcu_spi0/k3-am67a-beagley-ai-spidev0-mcu.dts .
```
4. Change the default `spi0` device to use this new device tree that supports the hardware SPI:
 - Edit the base device tree:

```
nano ~/dtb-6.1-Beagle/src/arm64/ti/k3-am67a-beagley-ai.dts
```
 - Find the `alias` section and change the `spi0` line as highlighted below:

```

aliases {
    serial0 = &wkup_uart0;
    serial2 = &main_uart0;
    serial3 = &main_uart1;
    serial6 = &main_uart6;
    mmc1 = &sdhci1;
    mmc2 = &sdhci2;
    rtc0 = &rtc;
    spi0 = &mcu_spi0;
    usb0 = &usb0;
    usb1 = &usb1;
    i2c1 = &mcu_i2c0;
};

```

- Save and close the file: CTRL+X, then Y.

5. Build and install the device tree from our modified sources:

```

(byai)$ cd ~/dtb-6.1-Beagle/
(byai)$ make
(byai)$ sudo make install_arm64

```

6. Enable the SPI overlay and configure buffer size:

```

(byai)$ nano /boot/firmware/extlinux/extlinux.conf

```

- In the (default) section at the bottom of the file, find the line starting with 'fdtoverlays' (may be commented out with a #). Change this line to be:
fdtoverlays /overlays/k3-am67a-beagle-ai-spidev0-mcu.dtbo
- If you already have overlays listed, append this new DTBO file to your existing line, space separated.
- For better performance, configure the SPI buffer size by appending the following to the end of the line "append console=...":
spidev.bufsiz=131072
- Our screen is 240x240 pixels at 16 bit colour depth = 115,200 bytes; so rounding up to nearest power of 2 (2^{17})
- It should now look like (changes highlighted; long line omits some content with ...)

```

label microSD (default)
    kernel /Image
    append console=ttyS2,115200n8 ... spidev.bufsiz=131072
    fdtdir /
    fdt /ti/k3-am67a-beagle-ai.dtb
    fdtoverlays /overlays/k3-am67a-beagle-ai-spidev0-mcu.dtbo

```

7. Reboot:

```

(byai)$ sudo reboot -f

```

8. Verify SPI shows up:

```

(byai)$ ls /dev/spidev*
/dev/spidev0.0 /dev/spidev0.2

```

- As noted by William Schmidt, spidev0.0 is the first device (our LCD), and if you want to connect a second device to the same SPI bus (using CE1) it will be accessed via spidev0.2.